

Project Based GIS: Geospatial data (II)

ENVIRON 761

Geospatial Applications for
Conservation & Land Management

Part 1 - recap

- Data is a central component in GIS analyses
- Finding data, while getting easier, remains a time consuming step
 - Familiarity with public domain sources helps
- Even after finding data, you need to understand the data and its limitations

Today...

- Data portals and clearinghouses
- Searching for specialized data
- An in-depth look at digital elevation data

Data as infrastructure

Federal Register

Vol. 59, No. 71

Wednesday, April 13, 1994

Presidential Documents

Title 3—

Executive Order 12906 of April 11, 1994

The President

Coordinating Geographic Data Acquisition and Access: The National Spatial Data Infrastructure

National Spatial Data Infrastructure (NSDI)

<http://www.fgdc.gov/nsdi/nsdi.html>

- National Geospatial Data Clearinghouse
- Spatial data standards
- National Digital Geospatial Data Framework &
- Partnerships for data acquisition

Other National SDI's

- “Geoconnections in **Canada**”
<http://geoconnections.nrcan.gc.ca/>
- **Australian** Spatial Data Infrastructure (ASDI)
<http://www.icsm.gov.au>
- **United Kingdom** Location Programme (UKLP)
<http://data.gov.uk/location/uk-location-programme>
- Spain: <http://www.ideo.es>
- Netherlands: <https://www.pdok.nl/>
- Brazil: <http://www.ibge.gov.br/english/>
- India: <https://nsdiindia.gov.in/nsdi/nsdiportal/index.jsp>

Portals: Geospatial “One-Stops”

- Provides users an organized, often searchable venue for locating and downloading data...
- Very useful, but often unsuccessful...

**National Geospatial Data
Clearinghouse (NGDC)**

• 1994

**Geospatial One-Stop
(GOS)**

• 2003

**[\(Geo\)Data.gov/
Geospatial Platform](http://(Geo)Data.gov/Geospatial Platform)**

• 2011

Conservation Geo-Portal

Metadata standards

1. Identification of the dataset
 - Originator/creator; how the data set is maintained
 - Publication title & date
 - Purpose & time period
2. Quality of the dataset
 - Consistent? Complete? How created...
 - Assessment statistics
3. Organization of the dataset
4. Spatial Reference
5. Attribute information
6. Distribution information/restrictions
7. Contact information

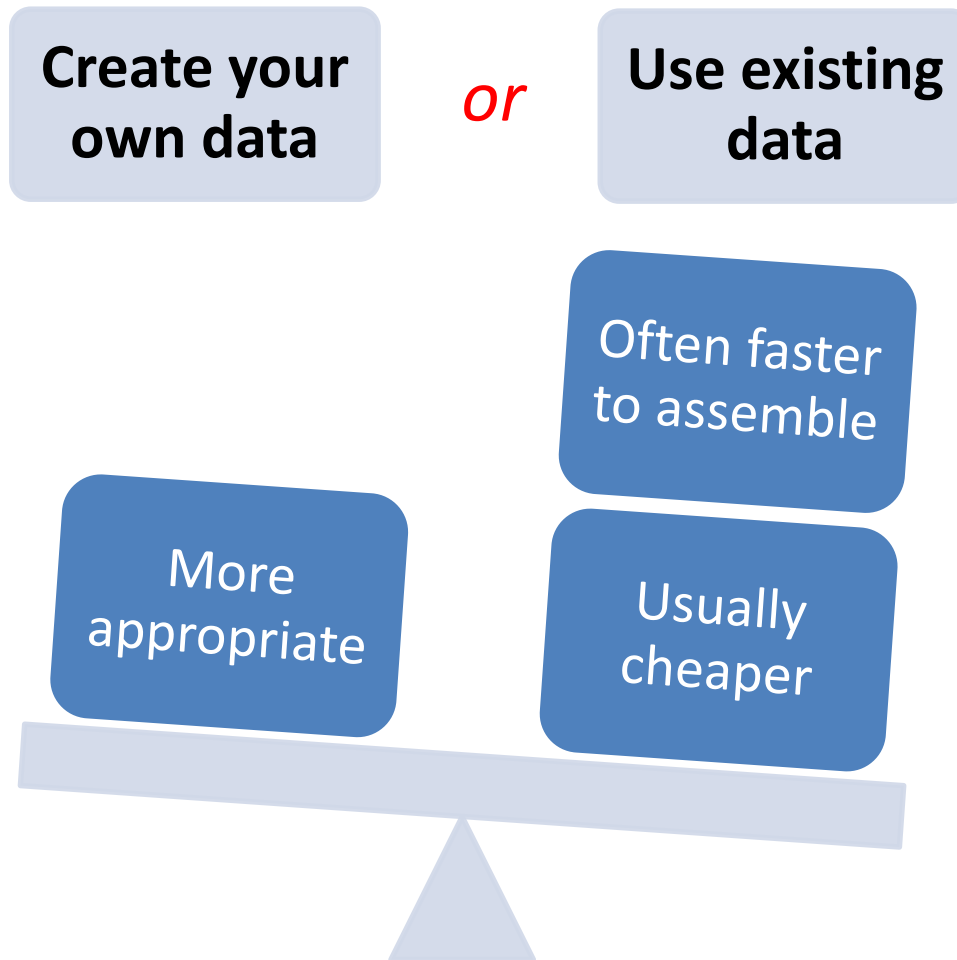
Useful Portals

Geospatial Portals

-  * <http://datagateway.nrcs.usda.gov/>
-  * <http://landcover.usgs.gov/index.php>
-  * <http://worldwildlife.org/pages/conservation-science-data-and-tools>
-  * <http://www.sage.wisc.edu/atlas/maps.php>
-  http://daac.ornl.gov/VEGETATION/vegetation_collections.shtml
-  <http://data.geocomm.com/>
-  <http://datadownload.unep-wcmc.org/datasets>
-  <http://datadownload.unep-wcmc.org/datasets>
-  <http://daymet.org/>
-  <http://gisinventory.net/>
-  <http://nationalmap.gov/viewer.html>
-  <http://serppas.org/Maps.aspx>
-  <http://water.usgs.gov/lookup/getgislist>
-  http://www.census.gov/geo/www/cob/bdy_files.html
-  <http://www.cgiar-csi.org/data>
-  <http://www.csc.noaa.gov/digitalcoast/data/index.html>
-  <http://www.databasin.org/>
-  <http://www.gap.uidaho.edu/>
-  http://www.nass.usda.gov/Research_and_Science/index.asp



Obtaining data: Considerations



Creating your own data

GIS Data Sources

Drew Decker

p. 37

Proper planning, though not too much—and I'll discuss this—is the key to building GIS databases. Building GIS databases is best described by breaking the process down into stages (we are assuming here that the data do not already exist, or if similar data do exist, that they do not meet our requirements):

1. Coordinate
2. Specify
3. Plan
4. Fund
5. Build
6. Distribute
7. Maintain

Volunteered Data

- USGS VGI resources
<http://cegis.usgs.gov/vgi/results.html>
- Presentations from a workshop at UC Santa Barbara in 2007
<http://ncgia.ucsb.edu/projects/vgi/products.html>
- Penn State Geography Department
<https://www.e-education.psu.edu/geog583/node/43>

eBird

<http://ebird.org>

The Cornell Lab of Ornithology

http://wiki.openstreetmap.org/wiki/Main_Page

OpenStreetMap
The Free Wiki World Map

iNaturalist.org

<http://www.inaturalist.org/>

<http://www.youtube.com/watch?v=8hhXZwLFfao>

Searching for data

GIS Data Law 3 Almost all GIS data have some value. Some data may require more manipulation but they can still make your GIS work better.

Decker, p. 35

Techniques for finding good spatial data:

- Knowing where to look...
 - Useful public domain datasets
 - Useful data portals/clearing houses
 - Web services
- Knowing how to look...
 - Web Search techniques

Web Searches

- Use keywords & search tricks:
 - “.shp|.e00|.zip” “shapefile” “ftp”
- Skim Metadata XML files
 - Search for “http://” or ftp://
- Dissect URLs to navigate to parent folders
- Use the Wayback machine... <http://archive.org/>

Elevation Data

Mendefera, Eritrea, Africa
IKONOS 0.8m Satellite Image
Over IKONOS 6m Stereo DEM
Date of Acquisition 10-Feb-2005

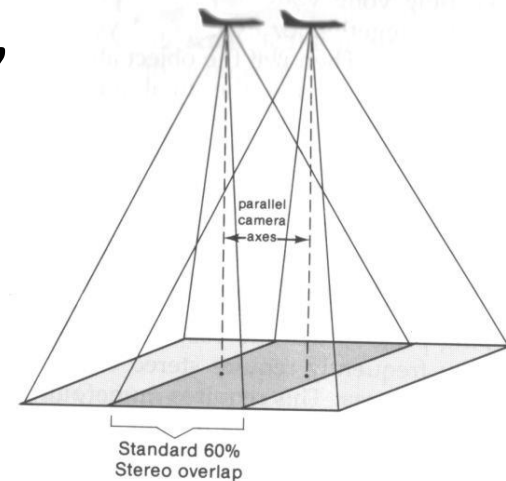


An in-depth look at one of the more
useful conservation data sets...

Where do elevation data come from?

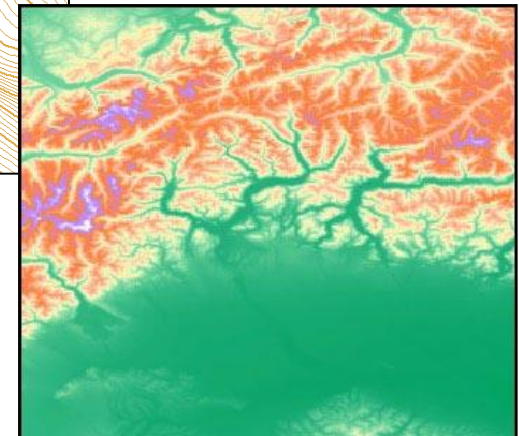
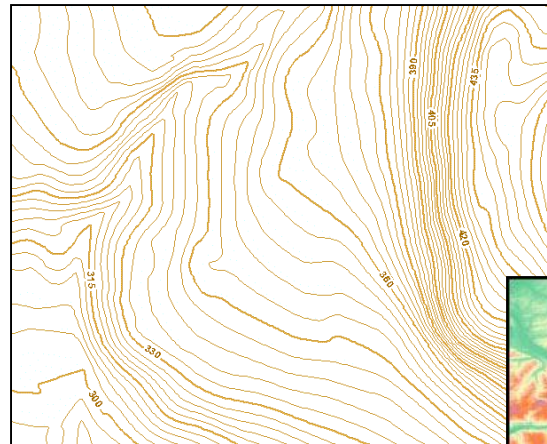
Increasing resolution
↓
Historical evolution

- Ground surveys:
Geodetic surveying: small number of points with high precision
- Overlapping air photos
- Overlapping satellite images
- Radar with 'dual antenna'
- LIDAR

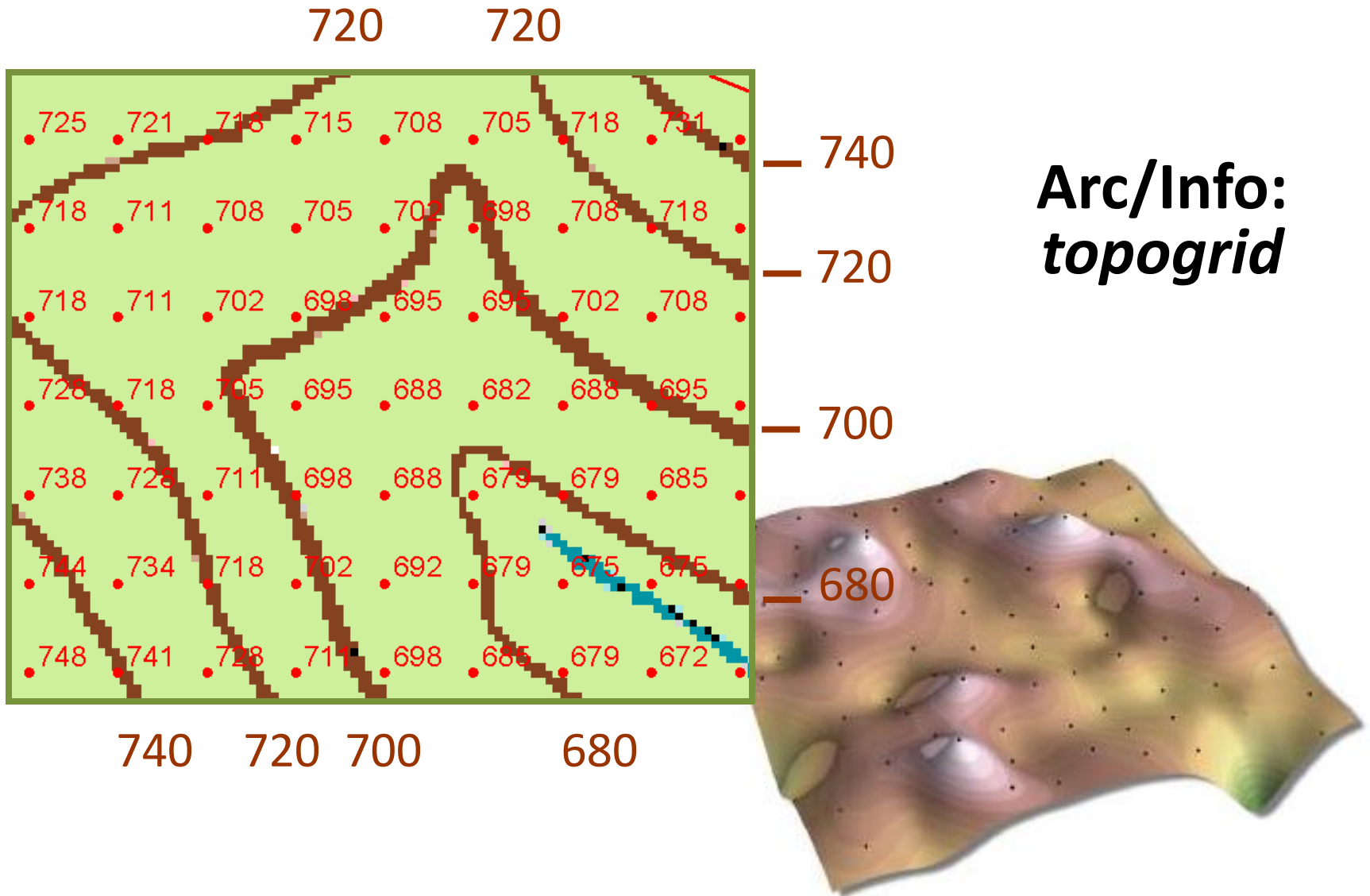


Photogrammetric processing

Parallax!



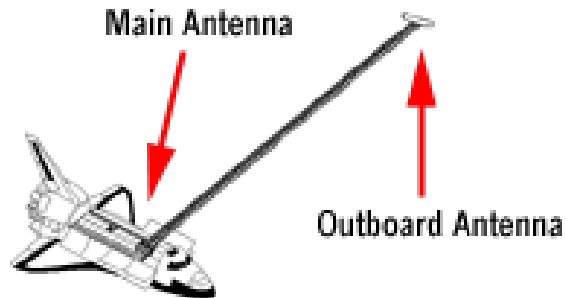
From contours to raster surfaces



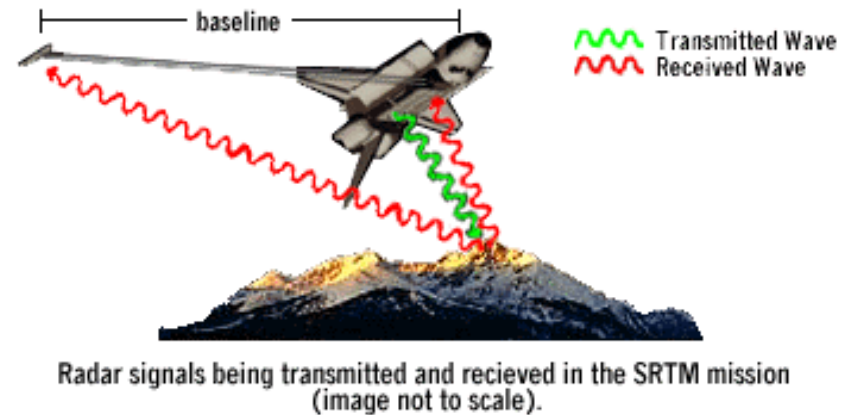
Shuttle Radar Topographic Mission (SRTM)



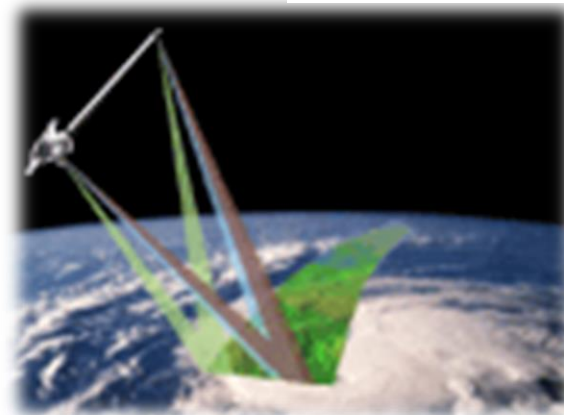
- US data = 1" resolution (approximately 30 m)
- Rest of the world = 3" or ~90m
- “Radar interferometry”



Reflected radar signals collected at two antennas, providing two sets of radar signals separated by a distance.



<http://srtm.csi.cgiar.org/>

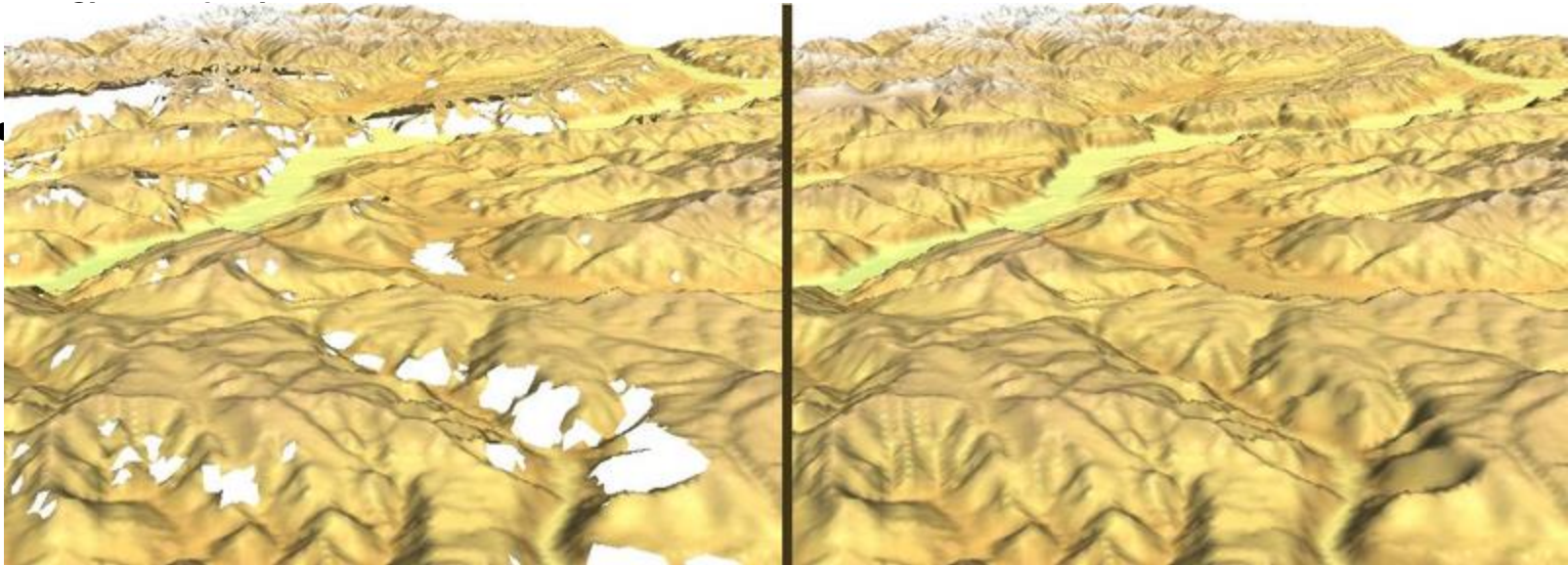


STRM data

- Collected from Space Shuttle Endeavor (Feb. 2000)
- 99.97% land mass covered at least once
 - 94.59% twice; 49.25% three x; 24.10% four x
- Geographic coordinate system used
 - WGS 84 horizontal datum; EGM96 vertical datum
- Errors from mast motion & phase noise errors
- Error tolerances:
 - 30 m ground sample distance
 - 16 m vertical height

SRTM issues

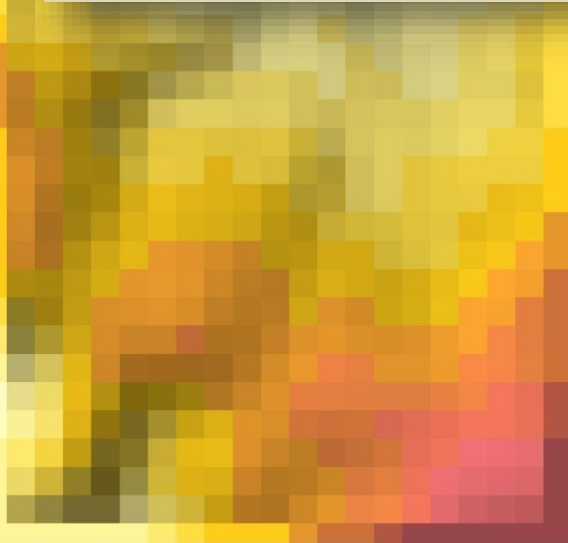
- Voids: "no-data" spaces (white below) where the water or the shadows obstructed the determination of the altitude.
- Canyons, mountain "shadows", lakes and large



Post-processed SRTM data

SRTM vs Photogrammetric derived DEMs

	NED	SRTM
Resolution	1 Arc Second (~ 30m resolution)	1 Arc Second (~30m resolution)
Source Data	Maps / Aerial Photos	Radar Images
Source Resolution	10m & 30m DEMs	30m
Source Dates	1925-1999	February, 2000 Space Shuttle Endeavor
Surface Type	"Bare Earth"	"First Return"
Accuracy Specifications	7m RMSE	10m RMSE



**SRTM at 3" res.
(about 90 m)
Hm = 1275.3**



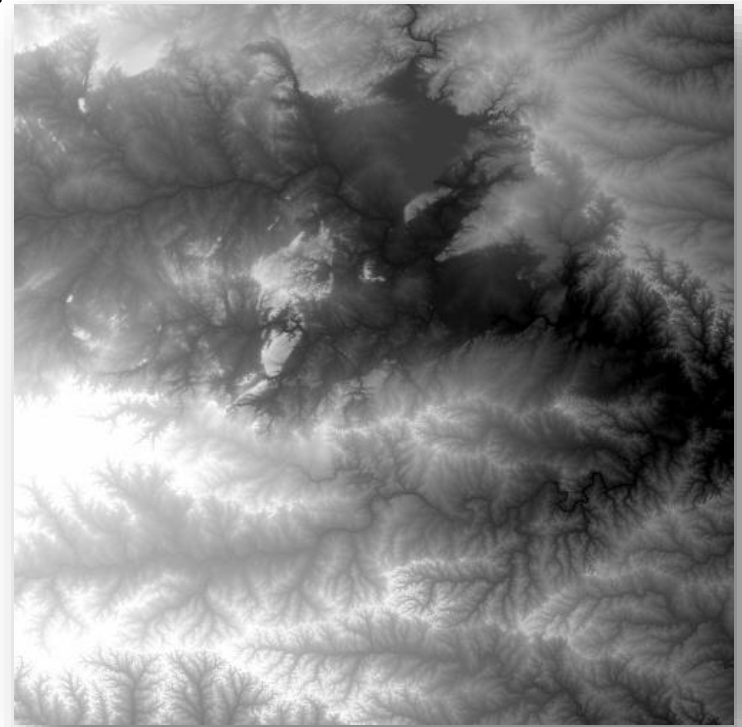
**SRTM at 30 m
from 3" SRTM
Hm = 1279.7**



**DTM from topo maps
at 1:25.000 scale
Hm = 1267.3**

National Elevation Dataset (originally)

- 1 arc-second ($\sim 30\text{m}$) resolution
- Seamless in 1° blocks for the United States
- 10 billion data
- Derived from USGS 1:24,000 quadrangle sheets



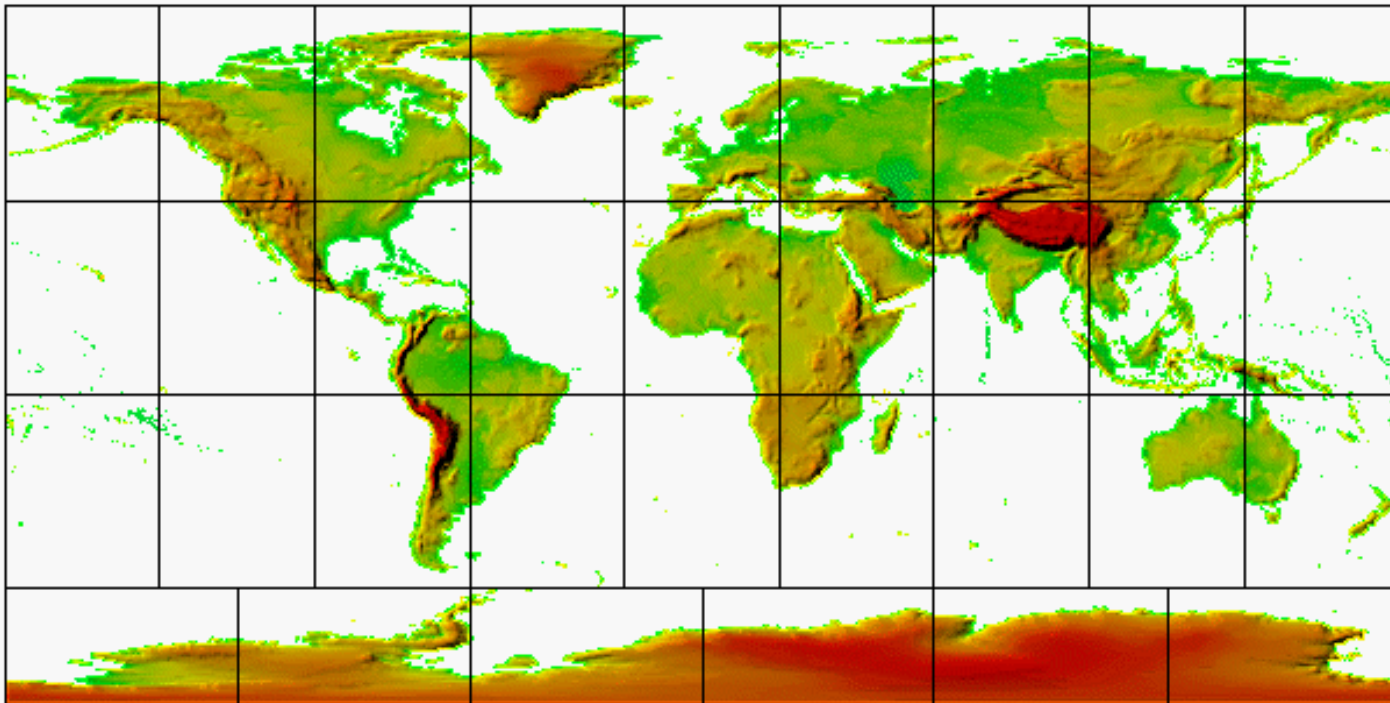
<http://seamless.usgs.gov/>

National Elevation Dataset (now)

- "Living dataset"
Best available raster elevation data of the conterminous United States, Alaska, Hawaii, and territorial islands
- Available nationally at resolutions of :
 - 1 arc-second (about 30 meters)
 - 1/3 arc-second (about 10 meters)
 - 1/9 arc-second (about 3 meters, in limited areas)
- Data provided in geographic coordinate system
 - NAD 83 horizontal datum; NAD 88 vertical datum
- Accuracy varies spatially b/c variable sources

Other DEM sources: GTOPO

- GTOPO – Global 30 arc-second (~1km)

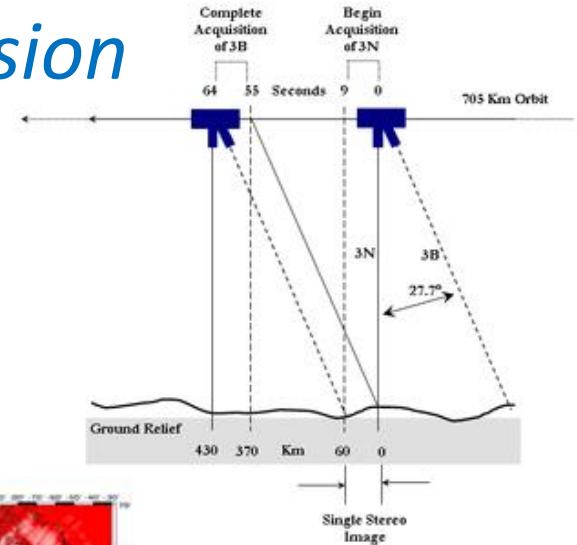


<http://eros.usgs.gov/products/elevation/gtopo30.php>

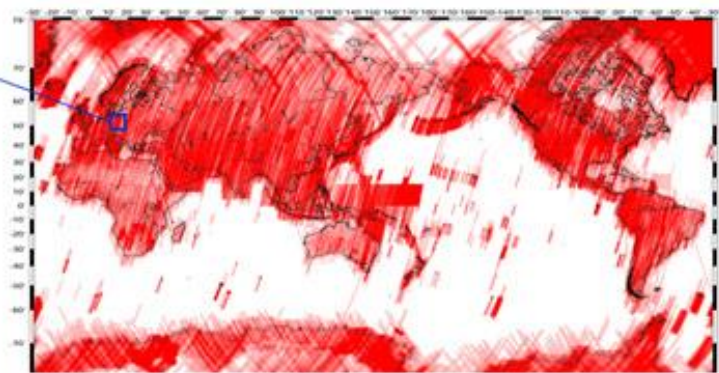
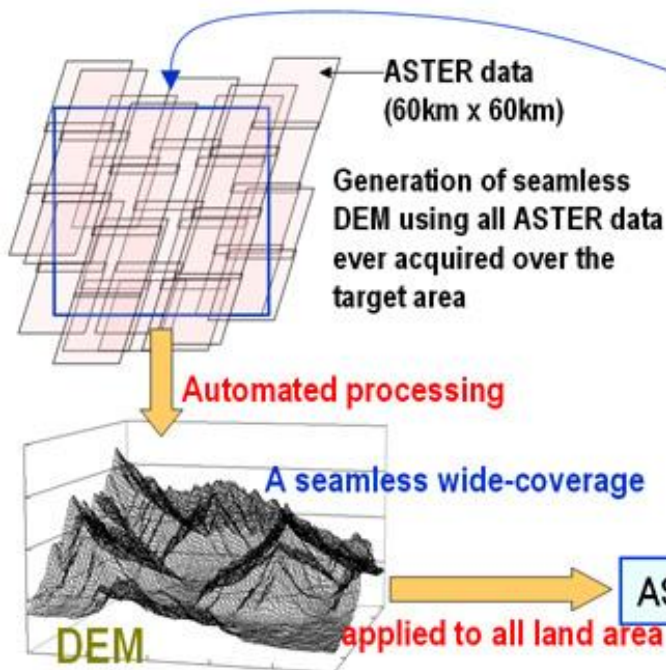
Other DEM data sources: **ASTER**

Advanced Spaceborne Thermal Emission & Reflection Radiometer

- 30 m resolution
- Seamless coverage : $83^{\circ}\text{N} \leftrightarrow 83^{\circ}\text{S}$



Track Imaging Geometry of the ASTER R Nadir and Backward-Viewing Sensors



Red-colored area: ASTER coverage (available area for GDEM generation) (Deeper red indicates more frequent observations, thus providing higher accuracy)

ASTER GDEM

Easy to use, allowing for selective cropping

ASTER data

- Multispectral imager launched by NASA in 1999
- Backward-looking near-IR band provides stereo coverage (i.e. ability to collect elevation data)
- Seamless coverage extending from 83°N to 83°S
 - 1.3 million scenes
- Data provided in 1x1° GeoTIFF tiles w/ 30m cells
 - GCS: WGS84 horiz. datum; EGM96 vert. datum
- 7 – 14m accuracy (varies by tile)
- *Version 1* of data release
 - Self described as "experimental" or "research grade"

Aster data – version 2

Released October 17th, 2011

Improvements in product quality due specifically to:

- the increased number of acquired ASTER stereo pairs
- refinements to the production algorithm (water masking, smaller correlation kernel size, bias removal).

These improvements include increased horizontal and vertical accuracy, better horizontal resolution, reduced presence of artifacts, and more realistic values over water bodies

Obtaining ASTER data

- <http://reverb.echo.nasa.gov>

The screenshot displays the NASA Earth Data Reverb | ECHO website interface. At the top, there is a navigation bar with links for NASA Earth Data, Data Discovery, Data Centers, Community, Science Disciplines, and Search EOSDIS. The NASA logo and "National Aeronautics and Space Administration" are on the left, and the "Reverb | ECHO" logo with the tagline "The Next Generation Earth Science Discovery Tool" is on the right. Below the navigation bar is a secondary menu with links for Home, About, Tutorial, Show Help, Shopping Cart (0), Order Status, Service Request Status, and Sign In.

The main content area is titled "Step 1: Select Search Criteria" and is divided into three main sections:

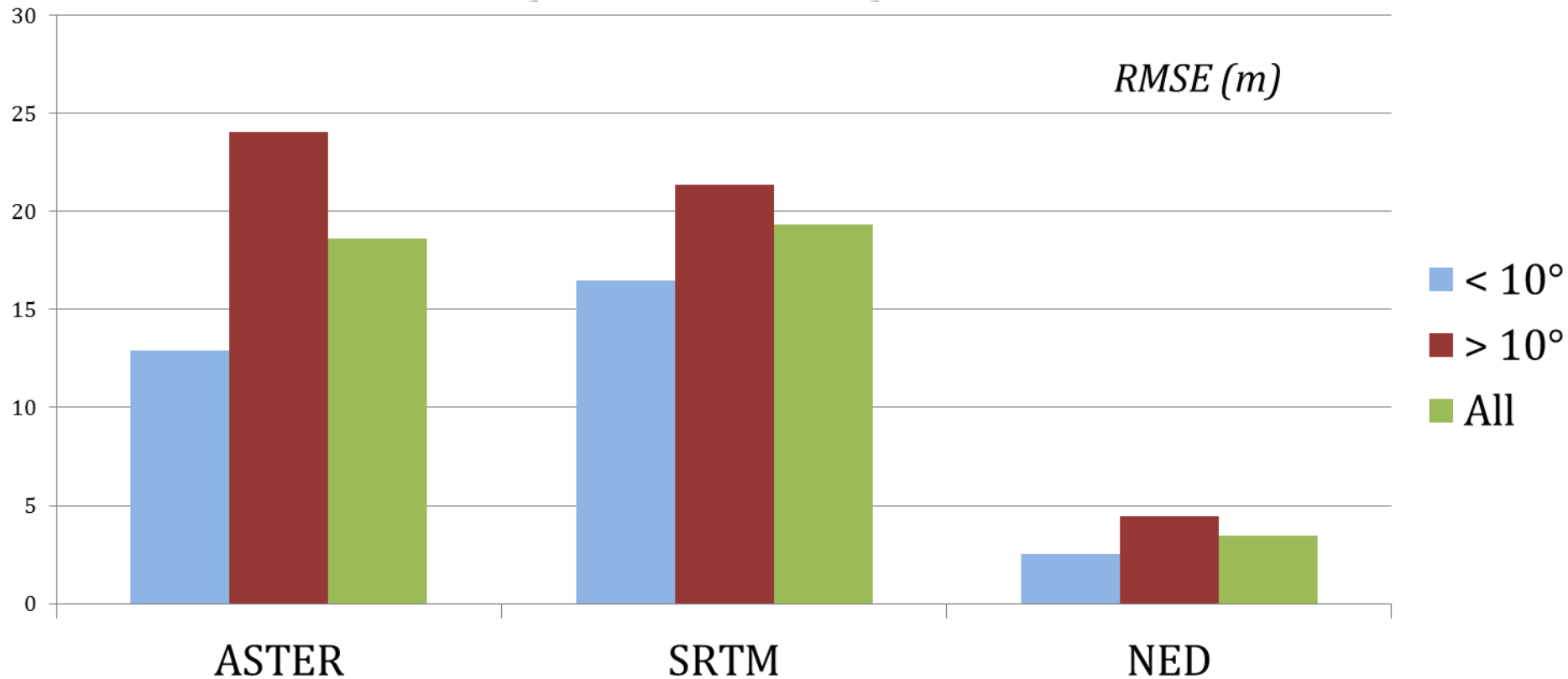
- Search Options:** A sidebar on the left with expandable sections for Spatial, Search Terms, Temporal, Platforms & Instruments, Campaigns, Processing Levels, and Science Keywords. It includes "Save Query" and "Clear Criteria" buttons, a "Feedback?" section, and an "Availability" section for the "ASTER GDEM V2 Tutorial" with a timestamp: "Mon Oct 17 2011 04:00:00 GMT-0400 (Eastern Daylight Time) (GMT-4:00) to (End Date Not Provided)".
- Spatial Search:** A central map area with a "Bounding Box" input field containing the example coordinates "e.g. -50.736, 163.477, -11.144, 105.680 (N,S,E,W)". It includes "Reset" and "Clear" buttons, a "Satellite" dropdown menu, and a Google map with a bounding rectangle tool. A text box says "Click and drag to set a bounding rectangle".
- Search Terms and Temporal Search:** On the right, there are input fields for "Search Terms" (with example "e.g. MODIS Fire AST_L1A") and "Temporal Search". The temporal search section has "START" and "END" fields, each with a calendar icon and a "Clear" button. A note states "* all times must be specified in GMT". At the bottom of this section are buttons for "Date Range" and "Annual Repeating Dates".

Comparing global digital elevation sources

	<i>ASTER GDEM</i>	<i>SRTM3</i>	<i>GTOPO30</i>
Data source	ASTER	Space shuttle radar	From organizations around the world that have DEM data
Generation and distribution	METI/NASA	NASA/USGS	USGS
Release year	2009 ~	2003 ~	1996 ~
Data acquisition period	2000 ~ ongoing	11 days (in 2000)	
Posting interval	30m	90m	1000m
DEM accuracy (stdev.)	7~14m	10m	30m
DEM coverage	83 degrees north ~ 83 degrees south	60 degrees north ~ 56 degrees south	Global
Area of missing data	Areas with no ASTER data due to constant cloud cover (supplied by other DEM)	Topographically steep area (due to radar characteristics)	None

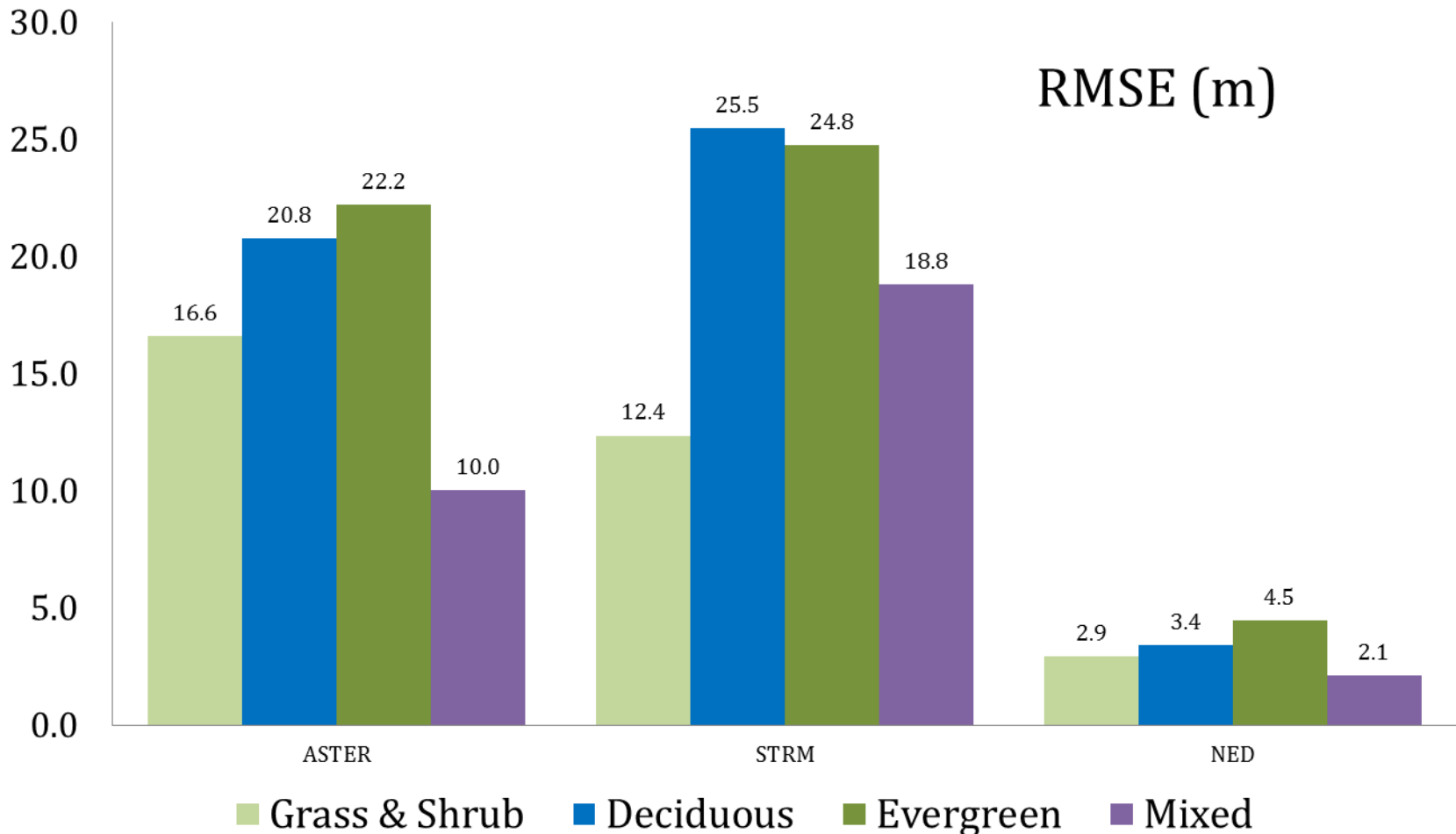
Comparing NED, STRM, ASTER

Table 3. Results of accuracy assessment of the remotely sensed DTMs versus the reference data for slopes less



Comparing NED, STRM, ASTER

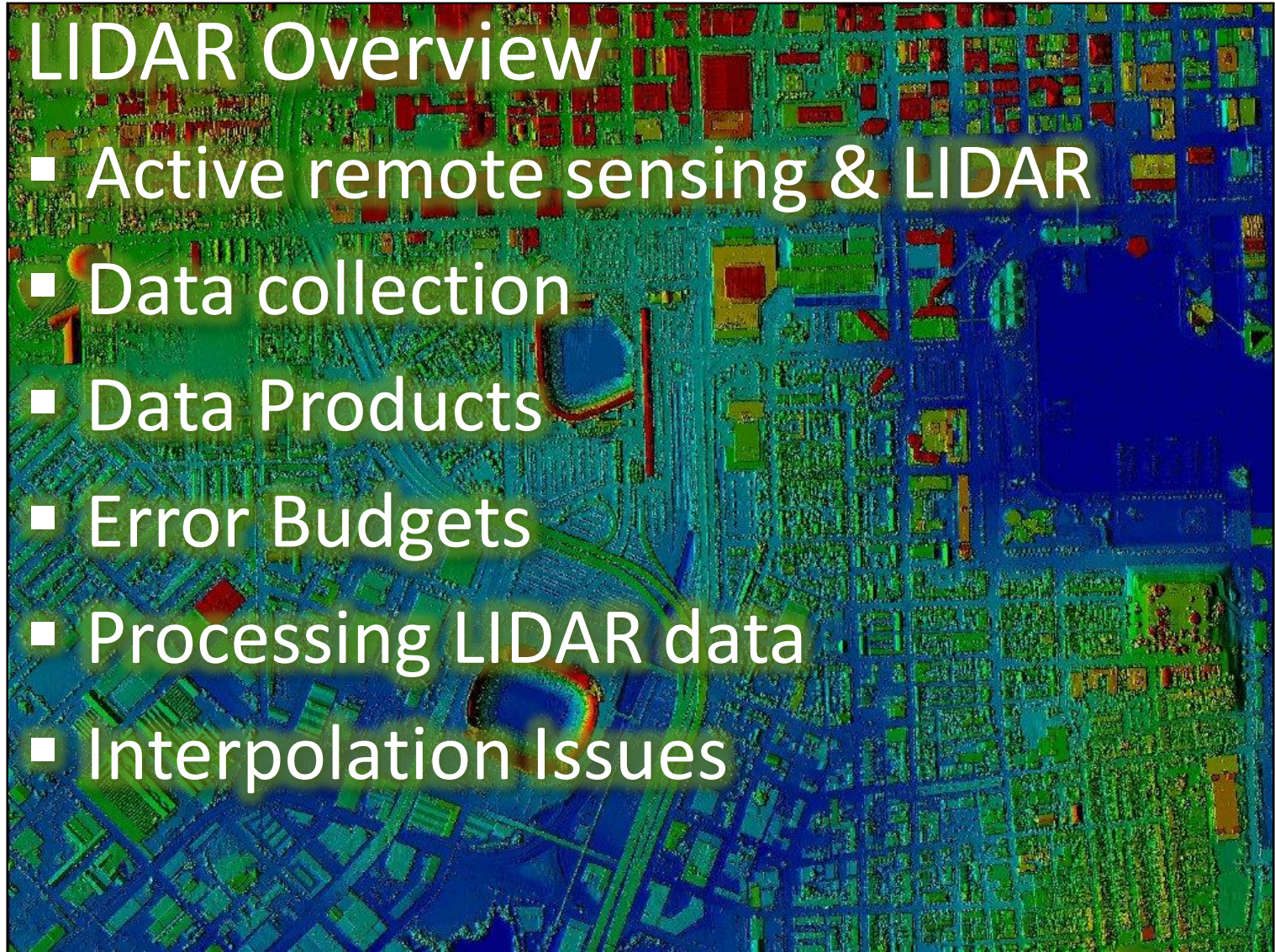
Table 4. Accuracy Assessment of DTMs with field collected GPS GCPs over the three land cover types.



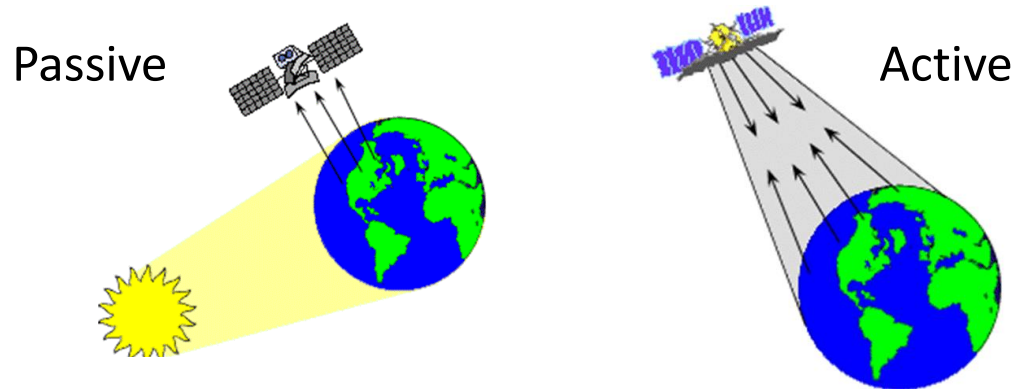
Light Detection and Ranging (LIDAR)

LIDAR Overview

- Active remote sensing & LIDAR
- Data collection
- Data Products
- Error Budgets
- Processing LIDAR data
- Interpolation Issues



Active vs. Passive Remote Sensing



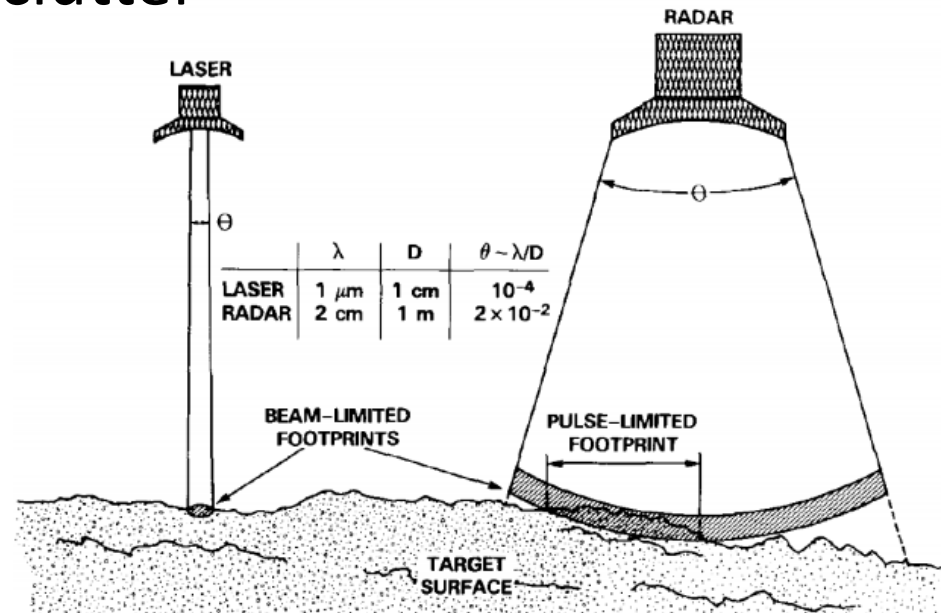
Active Remote Sensing

- Provides own source of energy for illumination
- Independent of natural light sources and time of day
- Reduced sensitivity to background light
- High intensity stimulating signal; less interference
- Control of stimulating signal
- Knowledge of stimulating signal

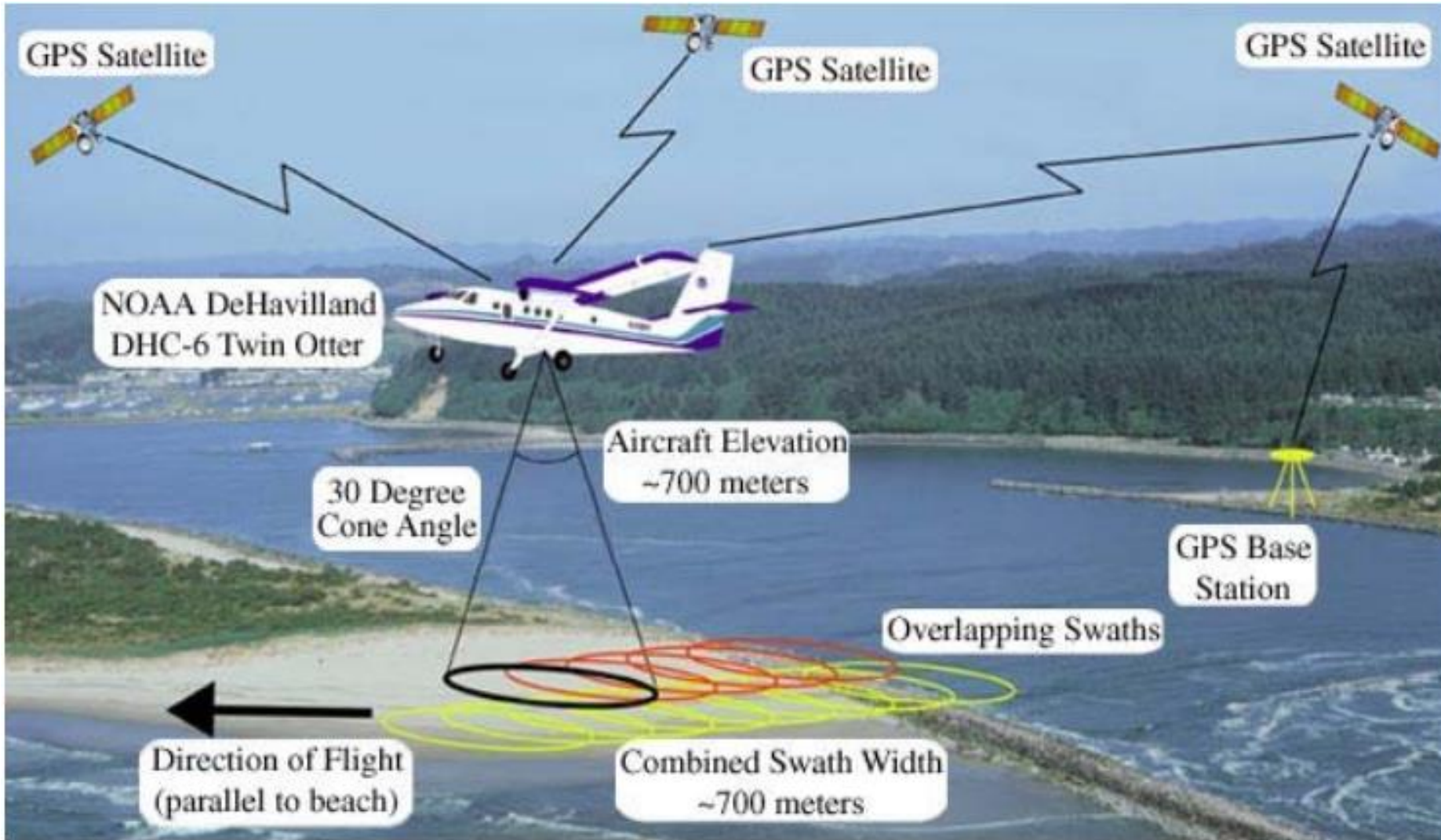
LIDAR vs. other active remote sensors

Lasers vs. microwaves (e.g. RADAR) or sound (SONAR)

- Easier aiming → better imaging
- Less diffraction → better spatial resolution
- Better angular range and Doppler resolution
- No sidelobes, no ground clutter
- Narrow spectrum → high coherence
- Tunable wavelength
- Polarization control
- No electromagnetic interference (EMI)

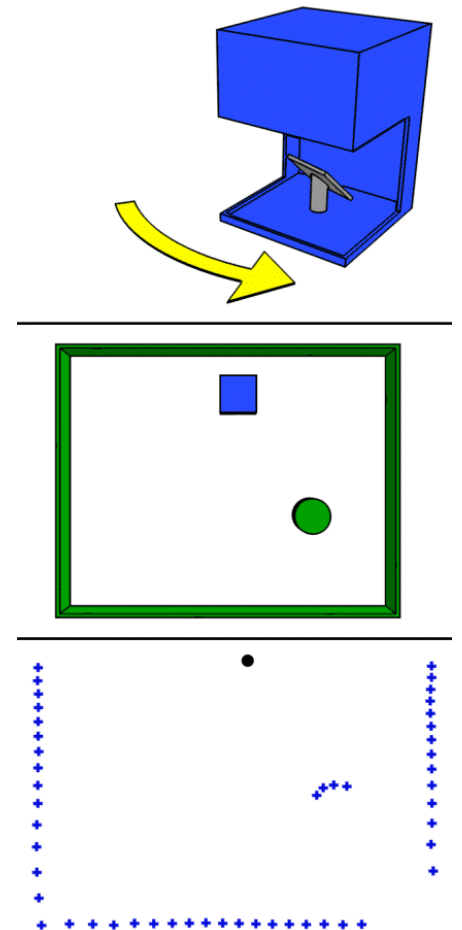
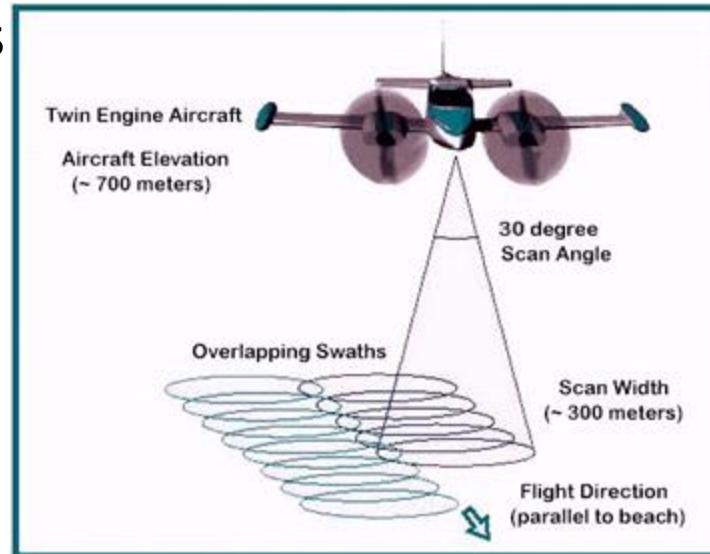


LIDAR: data collection



LIDAR: data collection

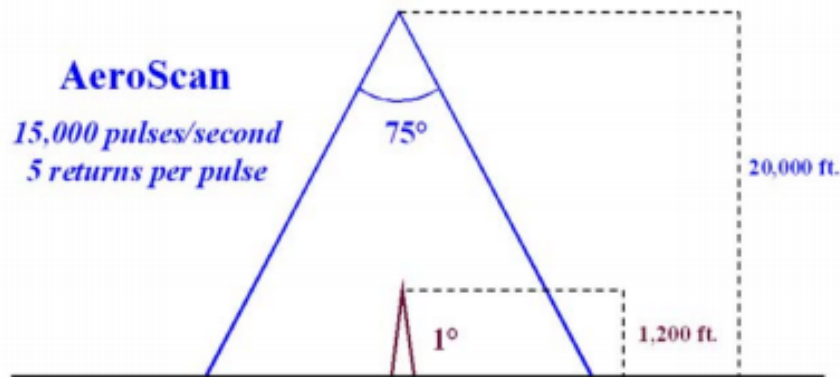
- System emits 5,000 – 50,000 pulses per second in a scanning array.
- Scanning angle, flying height, & airspeed determine point spacing .
- Pulses form a cylinder of light as rotating mirror deflects laser beam to ground



LIDAR: Altitude, posting, and accuracy

Flight Altitude	Post Spacing	Vertical/Horizontal Accuracy
20,000 feet	12 meters	±0.6/1.5 meters
12,000 feet	8 meters	±0.30/1.0 meters
8,000 feet	5 meters	±0.25/0.50 meters
4,000 feet	2 meters	±0.20/0.30 meters

Depending on the coverage and point density required, a scan rate and field of view setting can be set to obtain the optimal result. The LIDAR instrument's field of view can vary from 5 to 75 degrees.



(From: EarthData)

LIDAR: data collection

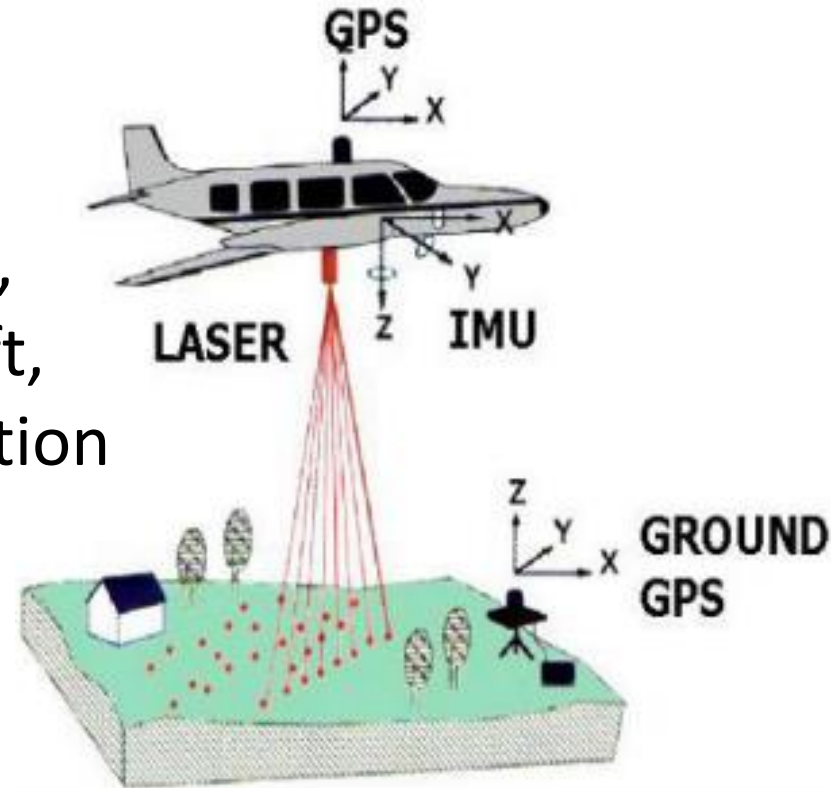
LIDAR Echo Time To Measurement Range Conversion

assume the speed of light, $c = 3.0 \times 10^8$ m/s

- 1 ns = 0.3 m = 11.8 inches
- 1 microsecond = 300 m = 984 feet
- 10 microseconds = 3 km = 1.86 statute miles = 1.61 nautical miles
- 100 microseconds = 30 km = 18.6 statute miles = 16.1 nautical miles
- 1 ms = 300 km = 186 statute miles = 161 nautical miles

LIDAR: data collection

- Onboard GPS determines the x, y, and z coordinates of the moving LIDAR sensor in the air, surveyed relative to one or more GPS base stations to increase precision.
- An Inertial Measuring Unit (IMU) directly measures the roll, pitch, and heading of the aircraft, establishing the angular orientation of the LIDAR sensor about the x, y, and z axes in flight.

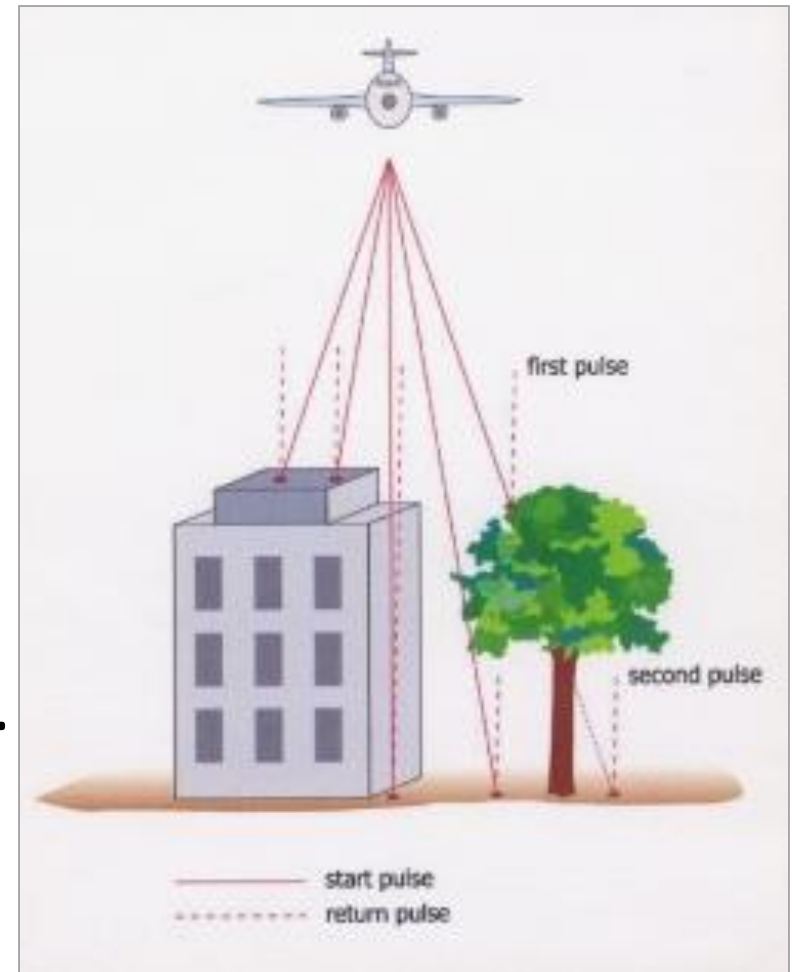


LIDAR: data collection

- The LIDAR sensor measures the scan angle of the laser pulses. Combined with the IMU data, this establishes the angular orientation of each laser pulse.
- The LIDAR sensor measures the time needed for each emitted pulse to reflect off the ground (or features thereon) and return to the sensor.

LIDAR data products: pulse returns

- Sensors can pick up multiple returns per pulse – up to 5.
- The first return is the first thing hit by the pulse (e.g. tree top, roof, bird in flight)
- If the target is soft, (e.g. forest canopy), some of the beam will penetrate giving a second return.
- The last return represents bare earth – *usually, but not always.*



Multiple LIDAR returns

Highest point
(first return)



Mid-level LIDAR



Bare Earth LIDAR



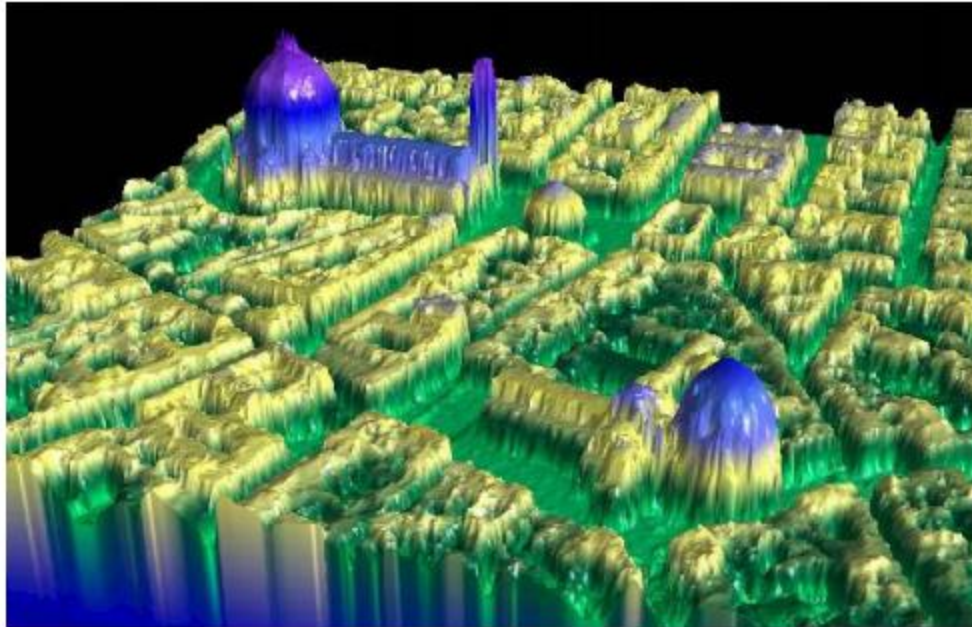
Images courtesy Great Britain Forestry Commission

<http://www.forestry.gov.uk/forestry/INFD-6RVC9J>

LIDAR: Post processing

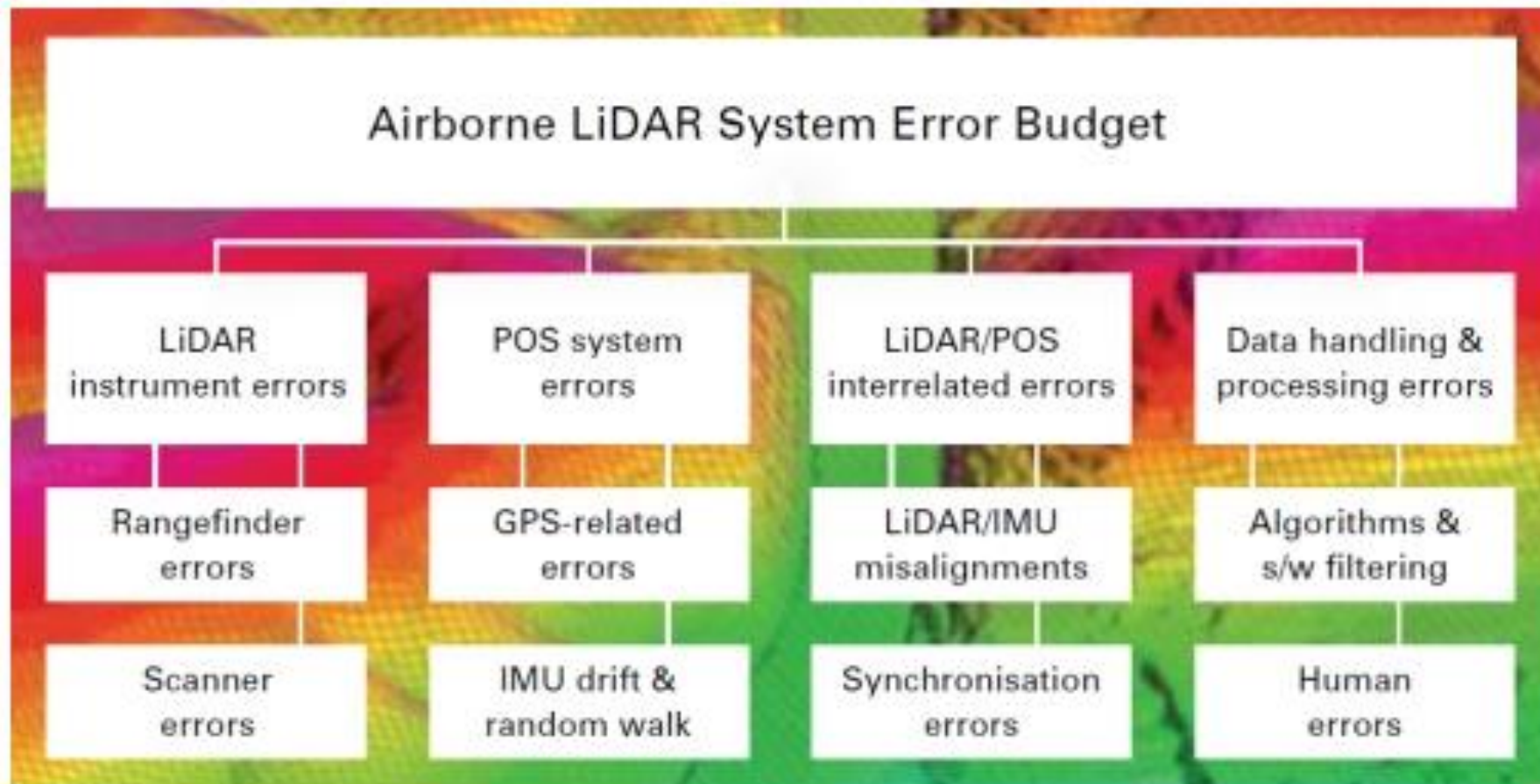
Need to filter out features you don't want to map:

Pre-Processed LIDAR Data in an Urban Area



- Automated post-processing to detect unnatural elevation changes (e.g. rooftops).
- Manual checking (against imagery) for more challenging circumstances (e.g. vegetation). \$\$

LIDAR: error budgets

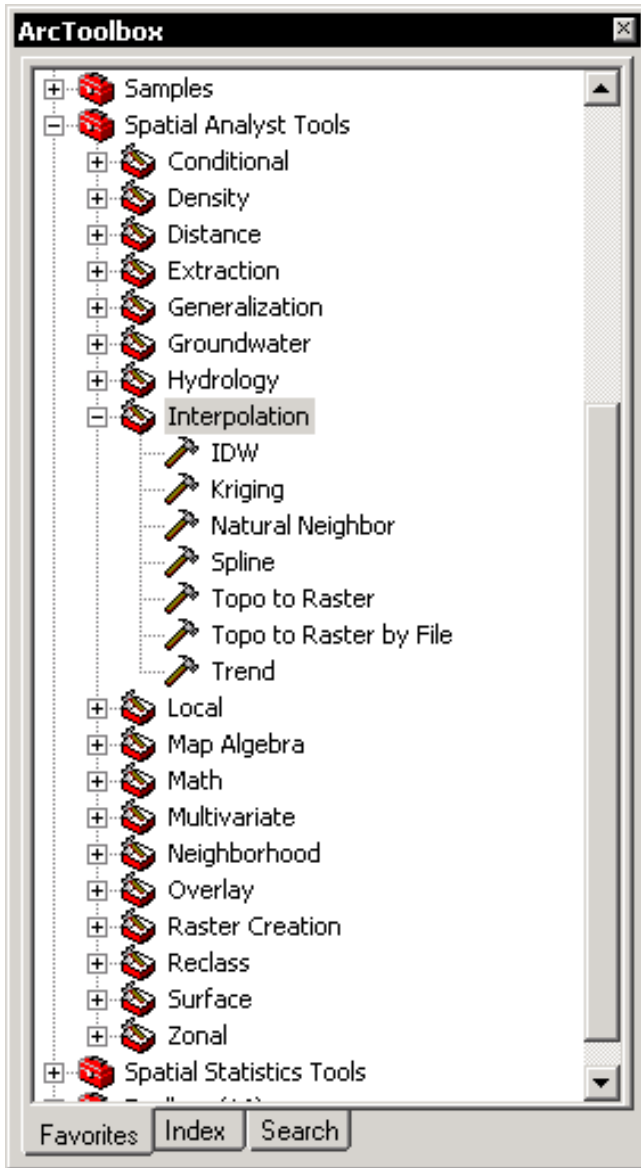


LIDAR: error budgets

- GPS Precision
- INS Precision
- LIDAR System Noise
- Timing Resolution
- Mechanical Tolerances (temperature, atmospheric pressure variations)
- Atmospheric Distortions (extreme ground temperature, haze).

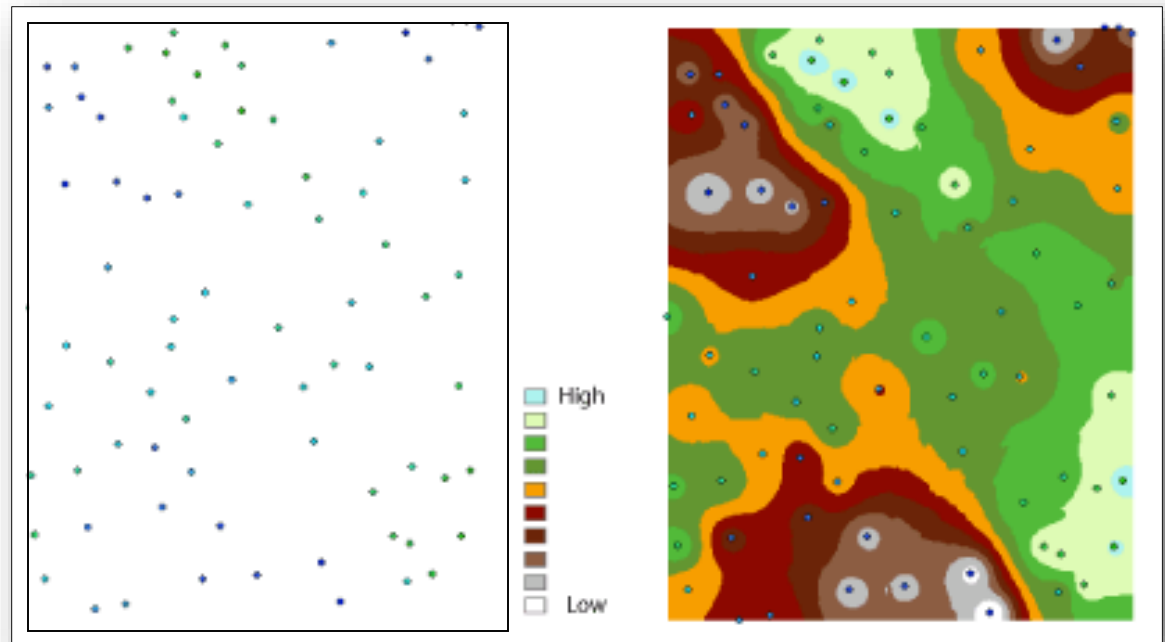
These factors typically add up to an error budget of ± 12 - 15 cm for LIDAR data collection flown at 5,000' AGL.

LIDAR Processing: Points to Surface

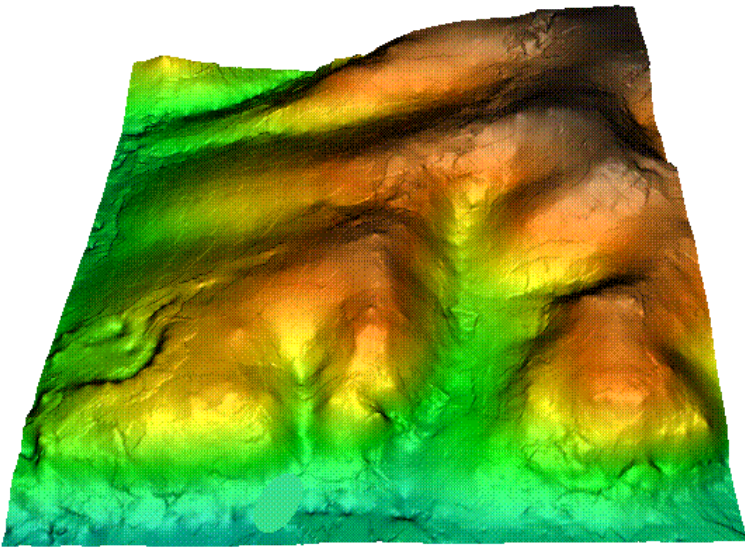


Spatial interpolation methods

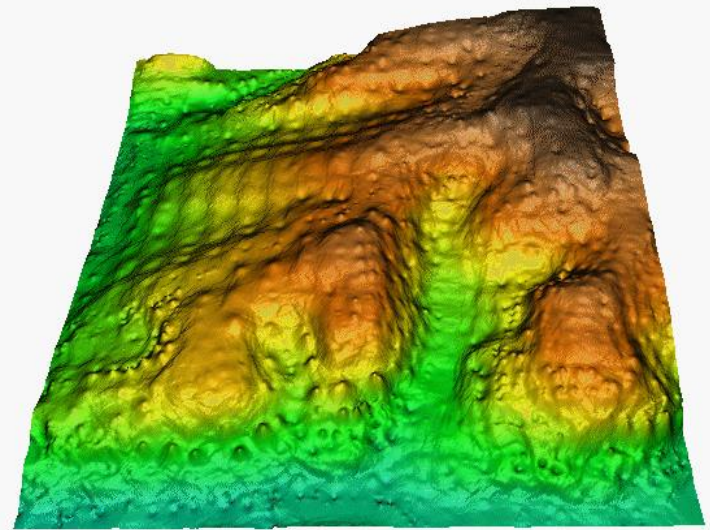
- Inverse Distance Weighting (IDW)
- Kriging
- Natural Neighbors
- Spline



LIDAR Processing: Points to Surface



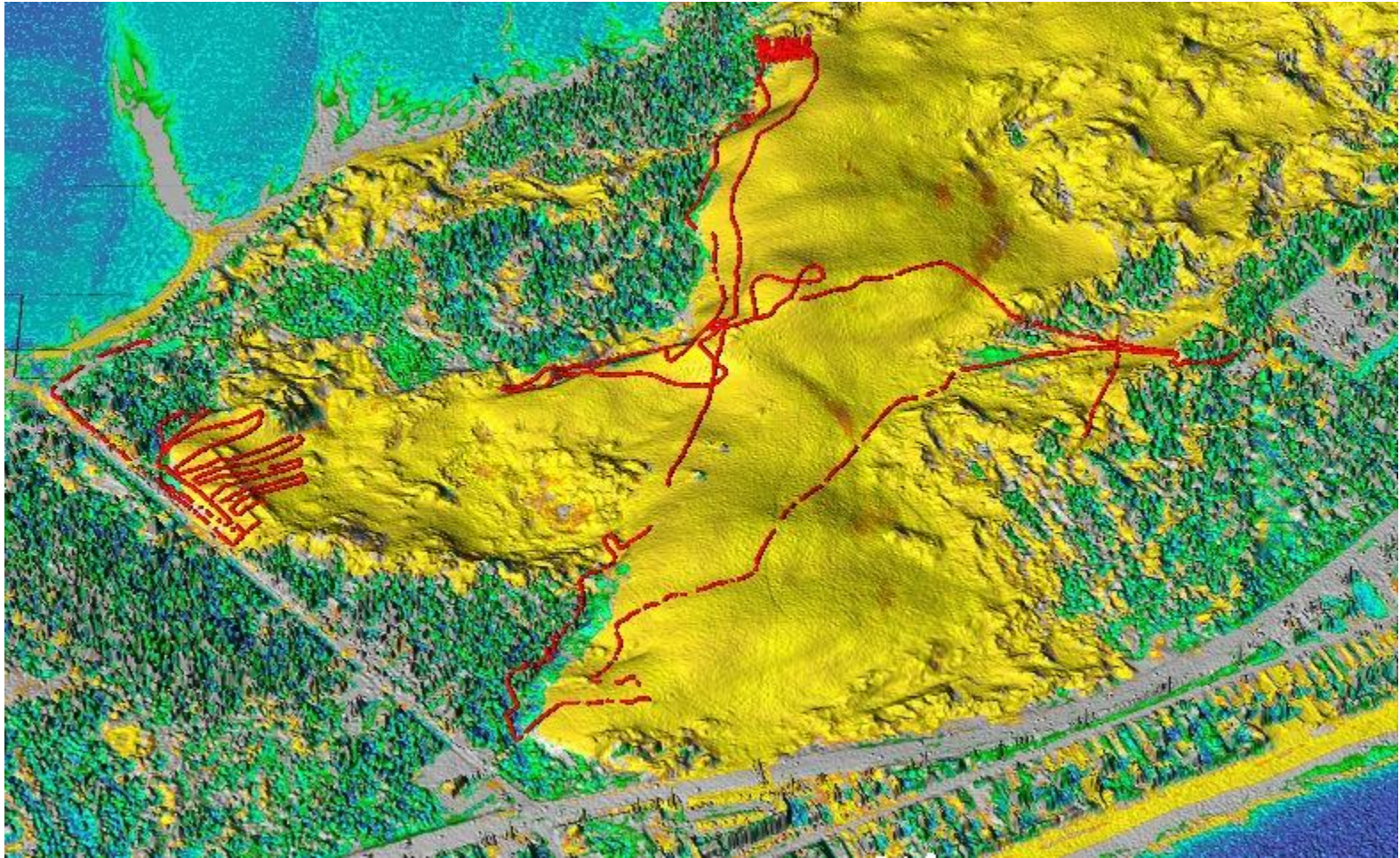
Spline



Inverse Distance Weighting (IDW)

Interpolation Matters

Combining 98 IR-DOQQ, 99 LIDAR and 02 RTK GPS
to assess the change: decreasing elevation, migration



Height
Year: m
1950: 43
1974: 34
1995: 27
1999: 26
2002: 24



LIDAR: Interpolation

Mitasova, et al 2005

- Importance of smoothing for the surface accuracy and noise reduction.
- Tension parameter is effective for tuning the level of detail in the elevation surface.

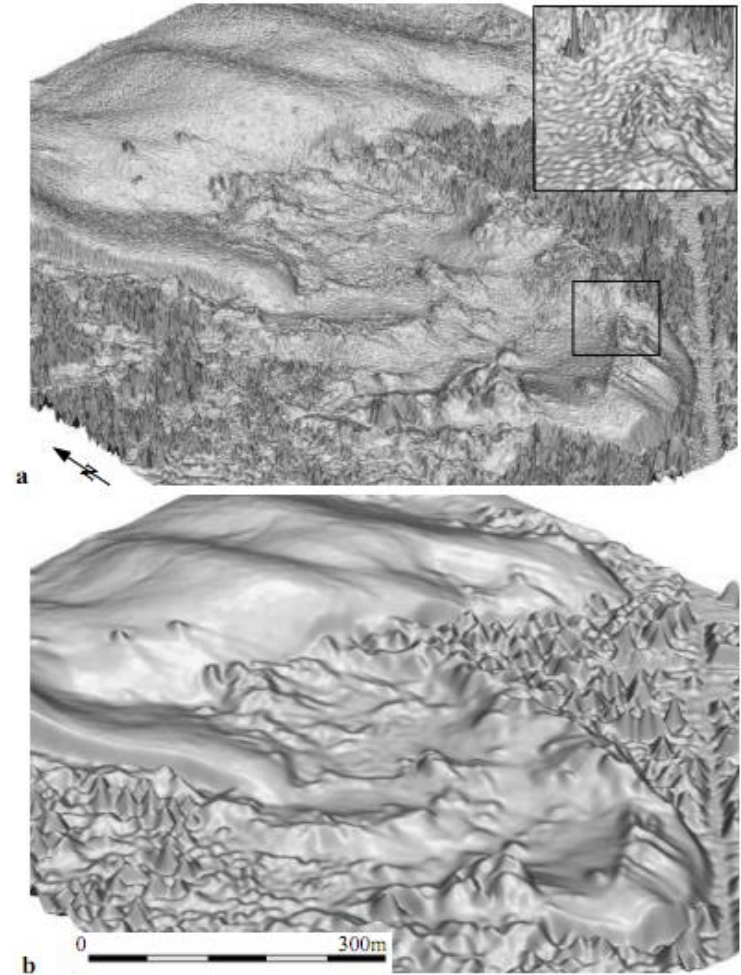
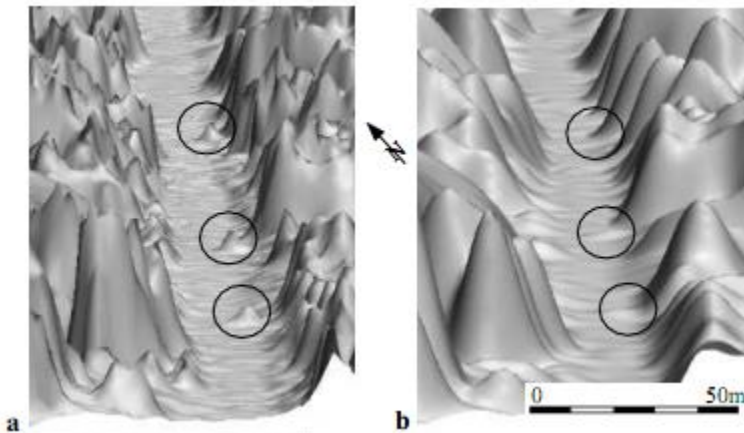
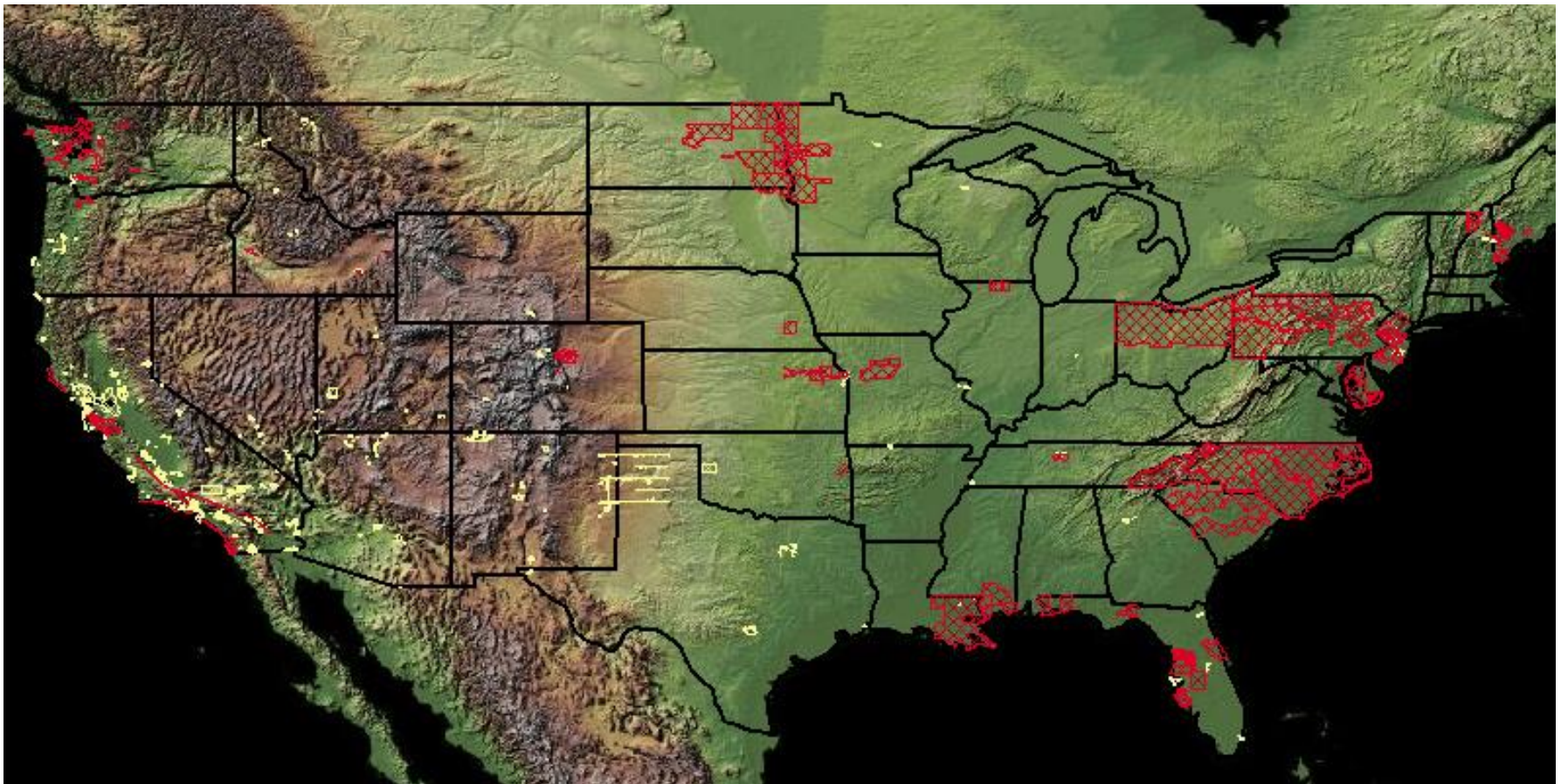


Fig. 2. Impact of tension φ and smoothing w on the 1999 DSM: (a) $\varphi = 400, w = 0.0$; insert shows overshoots for $\varphi = 100, w = 0.0$; (b) $\varphi = 100, w = 0.1$. The w and φ values are given for the RST implementation as *s.surf.rst* module run with the *-t* flag [16].

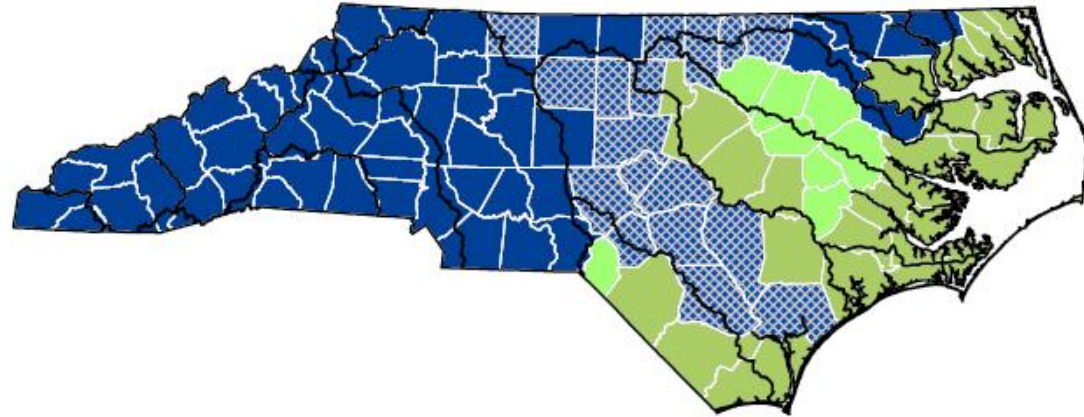
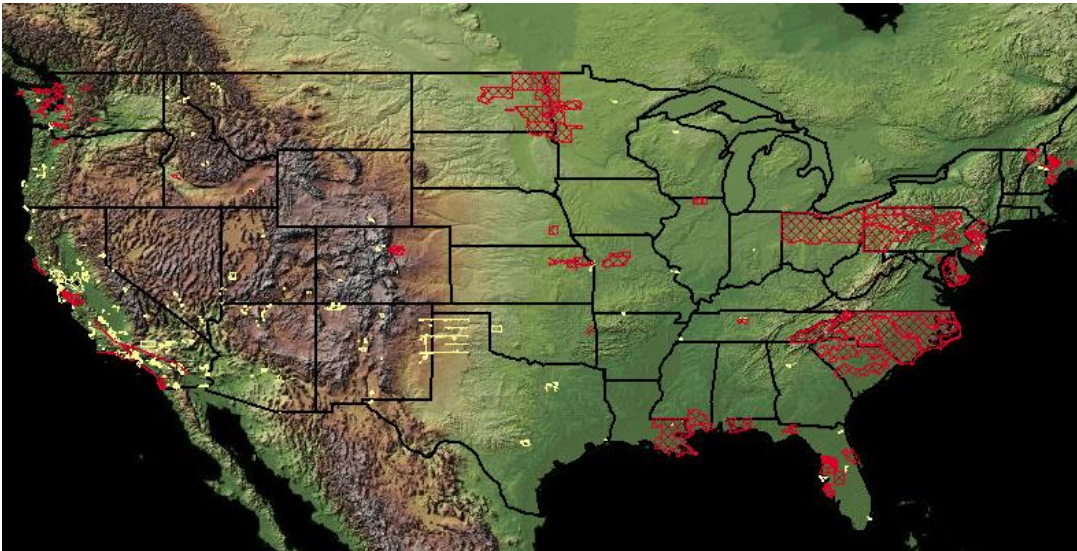
LIDAR: Data availability

http://lidar.cr.usgs.gov/LIDAR_View/viewer.php



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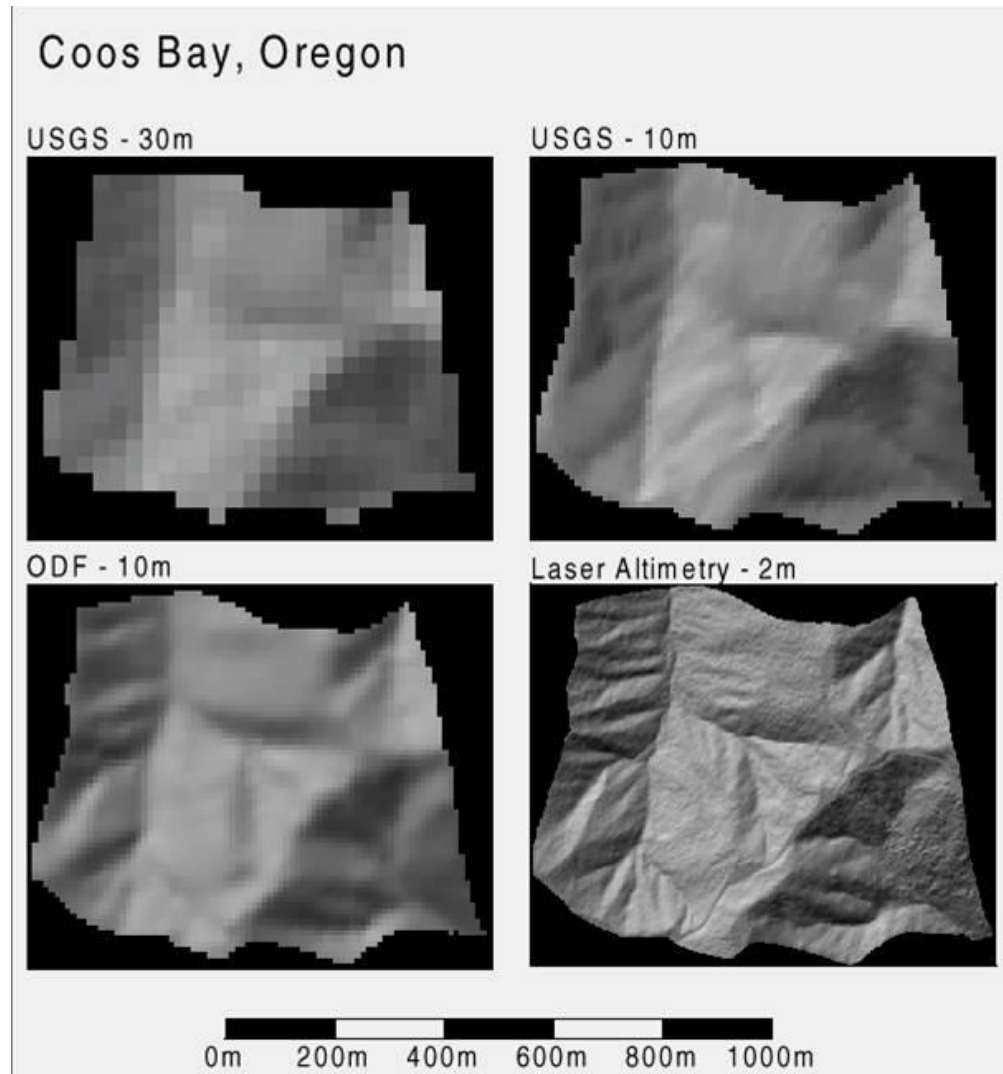
<http://www.ncfloodmaps.com/>

LIDAR: Advantages/Disadvantages

- Costly to acquire
- Costly to post-process
 - Weed points
 - Convert points to surface
- Steep learning curve to use
- Limited extent of available data

- + Massive amount of data collected fast
- + Superior resolution, detail
- + Multiple returns allows multiple outputs

*Comparison of a USGS 30-meter DEM (upper left), a USGS 10-meter DEM (upper right), a 10-meter DEM from the Oregon Department of Forestry (lower left) and a LIDAR-derived 2-meter DEM (lower right).
Courtesy of EarthData International.*



Some additional data links:

- NHD+: <http://www.horizon-systems.com/nhdplus/>
- EDNA: <http://edna.usgs.gov/>
- HydroSheds: <http://hydrosheds.cr.usgs.gov/>